

Hitchin Generalized Geometry.

ref: Hitchin IMS lecture in 2010

§ 1. Basic M^n

From T to $T \oplus T^* \ni X + \zeta$

$$(X + \zeta, X + \zeta) = 2_X \zeta \quad \text{Signature } (n, n).$$

Skew-adjoint endomorphism

$$\begin{pmatrix} A & \beta \\ B & -A^\sharp \end{pmatrix} \begin{pmatrix} T \\ T^* \end{pmatrix} \rightarrow \begin{pmatrix} T \\ T^* \end{pmatrix}$$

$$(B(X_1 + \zeta_1), X_2 + \zeta_2) = (B(X_1), X_2) = -(X_1, B(X_2))$$

$$\Rightarrow B: T \rightarrow T^* \text{ skew. i.e. } B \in \wedge^2 T^*$$

$$\begin{pmatrix} 0 & 0 \\ B & 0 \end{pmatrix}^2 = 0 \Rightarrow \text{orthogonal auto. } X + \zeta \mapsto X + \zeta + 2_X B$$

$$e^{\begin{pmatrix} 0 & 0 \\ B & 0 \end{pmatrix}} = I + \begin{pmatrix} 0 & 0 \\ B & 0 \end{pmatrix} \quad \text{B-field action.}$$

• Lie bracket \rightsquigarrow Courant bracket

$$[X + \zeta, Y + \eta]$$

$$= [X, Y] + \mathcal{L}_X \eta - \mathcal{L}_Y \zeta - \frac{1}{2} d(2_X \eta - 2_Y \zeta)$$

Jacobi identity is not satisfied. i.e. not Lie alg.

Prop: $[,]$ is preserved by closed B-fields.

$$\text{Pf. } [X + \zeta + 2_X B, Y + \eta + 2_Y B]$$

$$= [X + \zeta, Y + \eta] + \mathcal{L}_X (2_Y B) - \frac{1}{2} d(2_X 2_Y B)$$

$$- \mathcal{L}_Y (2_X B) + \frac{1}{2} d(2_Y 2_X B)$$

$$\underbrace{d 2_Y 2_X B}_{\mathcal{L}_Y (2_X B) - 2_Y d(2_X B)}$$

$$= [X + \zeta, Y + \eta] + 2_{[X, Y]} B + \underbrace{2_Y \mathcal{L}_X B - 2_Y d(2_X B)}_{2_Y 2_X dB} \quad (\because B: \text{closed}) \quad \#$$

Diff M $\times \Omega^2_{cl}$

fund. gp. which we can transf. by.

$$X + \zeta \in \Gamma(T \oplus T^*)$$

$$\mapsto X - d\zeta \in \text{Lie}(\Omega^2_{cl} \times \text{Diff}(M)) =: \mathfrak{g}$$

acts on section of $T \oplus T^*$

$$Y + \eta \curvearrowright \mathcal{L}_X(Y + \eta) - \mathcal{L}_X d\zeta =: uv \quad \begin{matrix} u = X + \zeta \\ v = Y + \eta \end{matrix}$$

Indeed, Courant bracket = $\frac{1}{2}(uv - vu)$

$$\begin{aligned} \frac{1}{2}(uv + vu) &= \frac{1}{2}(\mathcal{L}_X \eta - \mathcal{L}_Y d\zeta + \mathcal{L}_Y \zeta - \mathcal{L}_X d\eta) \\ &= \frac{1}{2} d(\mathcal{L}_X \eta + \mathcal{L}_Y \zeta) \\ &= d(u, v). \end{aligned}$$

Prop. $u(vw) = (uv)w + v(uw)$ i.e. derivation

Pf. Write $u = X + \zeta$ & $\tilde{u} = X - d\zeta$
 $u(vw) - v(uw) = \tilde{u}\tilde{v}(w) - \tilde{v}\tilde{u}(w) = [\tilde{u}, \tilde{v}](w)$ ← Lie bracket in \mathfrak{g}

$$[\tilde{u}, \tilde{v}] = [X, Y] - (\mathcal{L}_X d\eta - \mathcal{L}_Y d\zeta)(w)$$

$$uv = [X, Y] + \mathcal{L}_X \eta - \mathcal{L}_Y d\zeta, \text{ acts as } [X, Y] - d(\mathcal{L}_X \eta - \mathcal{L}_Y d\zeta)$$

$$\text{Note } d(\mathcal{L}_Y d\zeta) = \mathcal{L}_Y d\zeta - \cancel{\mathcal{L}_Y d^2 \zeta} \quad \#$$

Cor. For Courant bracket,

$$[[u, v], w] + \text{cyclic} = \frac{1}{3} d(\{[u, v], w\} + \text{cyclic}).$$

Pf. LHS: $\frac{1}{4} \begin{pmatrix} (uv - vu)w - w(uv - vu) \\ + (vw - wv)u - u(vw - wv) \\ + (wu - uw)v - v(wu - uw) \end{pmatrix} \rightsquigarrow (-1) \times \text{sum of right hand column.}$
↑
l ↑
r pair up

$$l + r = -r \quad \& \quad l - r = -3r = 3(l + r)$$

$$l + r = \frac{1}{3}(l - r) \frac{1}{4} \left\{ \begin{matrix} (uv - vu)w + w(uv - vu) \\ + \\ + \end{matrix} \right\} \rightarrow 4d([u, v], w) \quad \#$$

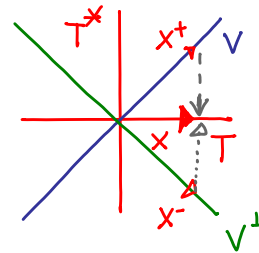
§ 2 Riemannian geometry.

$$g: T \rightarrow T^*$$

$$\frac{\partial}{\partial x_i} \mapsto g_{ij} dx_j$$

$V :=$ graph of $g \subset T \oplus T^*$
subbd.

$V^\perp :=$ graph of $(-g)$.



Prop: If v is a section V
 X vector field.

$$\nabla_x v := \underbrace{\pi_V [X^-, v]}_{\text{proj. onto } V} \text{ Courant.}$$

is a connection,
preserves inner product
induced on V .

reason: Properties of Courant bracket.

$$[u, fv] = f[u, v] + (Xf)v - (u, v)df.$$

$$X(v, w) = ([u, v] + d(u, v), w) + (v, [u, w] + d(u, w))$$

In fact, only need symmetric part of g to be pos. def.
 $\text{Tor } \nabla = d(\text{skew}(g)).$

$$\left[\underbrace{\frac{\partial}{\partial x_i} - g_{il} dx_l}_{X^- \in V^\perp}, \underbrace{\frac{\partial}{\partial x_j} + g_{jk} dx_k}_{\in V} \right]$$

$$= \frac{\partial g_{jl}}{\partial x_i} dx_l + \frac{\partial g_{il}}{\partial x_j} dx_l - \frac{1}{2} \frac{\partial}{\partial x_l} (g_{ji} + g_{ij}) dx_l$$

projection on V , (assume $g_{ij} = g_{ji}$)

$$\pi_V(dx_l) = \frac{1}{2} (dx_l + g^{lu} \frac{\partial}{\partial x_u})$$

$$\leadsto \frac{1}{2} g^{lk} \left(\frac{\partial g_{jl}}{\partial x_i} + \frac{\partial g_{il}}{\partial x_j} - \frac{\partial g_{ij}}{\partial x_l} \right) (g_{ui} dx_i + \frac{\partial}{\partial x_u})$$

\leadsto Christoffel symbol.

2. Bianchi IX metric

$$dt^2 + a_1^2 \sigma_1^2 + a_2^2 \sigma_2^2 + a_3^2 \sigma_3^2$$

σ_i 's: inv. forms
on $SU(2)$

$$a_i = a_i(t)$$

$$\mathcal{L}_{X_2} \sigma_1 = \sigma_3$$

$$d\sigma_1 = \sigma_2 \wedge \sigma_3$$

X_i : dual v.f. basis.

Courant bracket helpful for computations.

$$\text{eg. } \nabla_{X_1}(a_2 \sigma_2) = [X_1 - a_1^2 \sigma_1, a_2 \sigma_2 + \frac{1}{a_2} X_2]$$

$$= \pi_V \left[-\frac{X_3}{a_2} - a_2 \sigma_3 + \frac{a_1^2}{a_2} \sigma_3 \right]$$

$$= -\frac{X_3 - a_3^2 \sigma_3}{a_2} - a_2 \sigma_3 + \frac{a_1^2}{a_2} \sigma_3 + \dots$$

$$\Rightarrow \nabla_{X_1}(a_2 \sigma_2) = \frac{1}{2} \left(\frac{a_1^2}{a_2} - a_2 - \frac{a_3^2}{a_2} \right) \sigma_3$$

§ 3 Spinors $\varphi \in \Lambda^1 T^*$

$$T \oplus T^* =: \mathcal{U} \ni X + \zeta$$

$O(n, n)$

$$(X + \zeta) \cdot \varphi := \iota_X \varphi + \zeta \wedge \varphi$$

$$(X + \zeta)^2 \cdot \varphi = \dots = (\iota_X \zeta) \varphi = (X + \zeta, X + \zeta) \varphi$$

\leadsto Clifford alg. action

$$\mathcal{Cl}(\mathcal{U}) \quad uv + vu = 2(u, v)$$

$CL(\mathcal{U})$ anti-auto bilinear form
 $x_1 \dots x_n \rightarrow x_n \dots x_1$
 $a \mapsto a^T$

$$S = \text{Spin rep.} = \Lambda^1 T^* \otimes (\Lambda^n T^*)^{1/2}$$

bilinear form $(\varphi_1, \varphi_2) \stackrel{\Delta}{=} \sum (-1)^j (\varphi_1^{2j} \varphi_2^{n-2j} + \varphi_1^{2j+1} \varphi_2^{n-2j-1}) \in \mathbb{R}$
 Mukai pairing.

Lie algebra of $SO(n, n) \subset CL(\mathcal{U})_{= \mathcal{U}}$

is $\{a: [a, \mathcal{U}] \subset \mathcal{U} \text{ \& } a = -a^T\}$

$$B \in \Lambda^2 T^*$$

$$B \wedge (\iota_X + \zeta) \varphi - (\iota_X + \zeta) B \wedge \varphi$$

$$= -(\iota_X B) \varphi - \cancel{B \wedge \iota_X \varphi} + \cancel{B \wedge \iota_X \varphi}$$

$$\Rightarrow B\text{-field action on spinor} = \varphi \mapsto e^{-B \wedge} \varphi$$

$\Omega_{ce}^2 \times \text{Diff}(M)$ action on spinor is

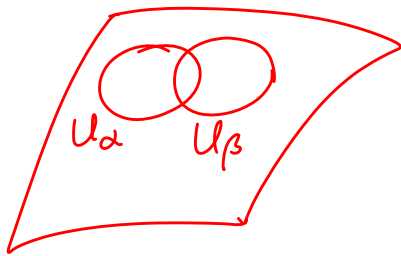
$$\mathcal{L}_X \varphi + d\xi \wedge \varphi$$

Cartan-like formula,

$$d(X+\xi) \cdot \varphi + (X+\xi) \cdot d\varphi = \underbrace{d\mathcal{L}_X \varphi + \mathcal{L}_X d\varphi}_{\mathcal{L}_X \varphi} + d\xi \wedge \varphi$$

§ Twisted structures

$T \oplus T^*$, $(,)$, $[,]$: preserved by closed B-field.



$$B_{\alpha\beta} \in \Omega_{ce}^2(U_\alpha \cap U_\beta)$$

$$B_{\alpha\beta} + B_{\beta\gamma} + B_{\gamma\alpha} = 0 \text{ on } U_\alpha \cap U_\beta \cap U_\gamma$$

$$(T \oplus T^*)|_{U_\alpha} \cong (T \oplus T^*)|_{U_\beta}$$

↑ identified by $X+\xi \mapsto X+\xi + 2X B_{\alpha\beta}$

\leadsto give us a VB E , locally modelled on $T \oplus T^*$.

$$0 \rightarrow T^* \rightarrow E \rightarrow T \rightarrow 0$$

E equips w/ $(,)$ & $[,]$.
Exact Courant algebroid.

exact seq. of sheaves, $0 \rightarrow \Omega_{ce}^2 \rightarrow \Omega^2 \rightarrow \Omega_{ce}^3 \rightarrow 0$

$$[B_{\alpha\beta}] \in H^1(\Omega_{ce}^2) = H^0(\Omega_{ce}^3) / dH^0(\Omega^2) = H^3(M, \mathbb{R}).$$

$(E, (,)) \leadsto$ Spinor bdl S

$$\Lambda^0 T^*|_{U_\alpha} \cong \Lambda^0 T^*|_{U_\beta} \text{ via } \varphi \mapsto e^{-B_{\alpha\beta}} \varphi$$

$$e^{B_{\alpha\beta}} d(e^{-B_{\alpha\beta}} \varphi) = d\varphi \quad (\because dB_{\alpha\beta} = 0)$$

$$d: C^\infty(S^{\text{ev}}) \rightarrow C^\infty(S^{\text{odd}})$$

\leadsto twisted deRham cohomology.

$$0 \rightarrow T^* \rightarrow E \rightarrow T \rightarrow 0$$

← isotropic splitting

$$\sim F_\alpha \in \Omega^2(U_\alpha) \quad \text{s.t.} \quad B_{\alpha\beta} = F_\beta - F_\alpha$$

$$H := dF_\alpha = dF_\beta \quad (\because dB_{\alpha\beta} = 0)$$

$$H \in \Omega^3(M).$$

Section of S , i.e. φ_α : forms on U_α s.t.
 $\varphi_\alpha = e^{-B_{\alpha\beta}} \varphi_\beta$ on $U_\alpha \cap U_\beta$
 $\Rightarrow e^{-F_\alpha} \varphi_\alpha = e^{-F_\beta} \varphi_\beta \rightsquigarrow$ global form ψ

If $d\varphi_\alpha = 0$, then $d\psi = -(dF_\alpha)\psi$
i.e. $(d+H)\psi = 0$.

Remark: Such H 's arises in genbes.

<p>Genbes. $U(1)$-genbe</p> <p>$g_{\alpha\beta\gamma} : U_\alpha \cap U_\beta \cap U_\gamma \rightarrow U(1)$</p> <p>Connection structure</p> <p>$A_{\beta\gamma} + A_{\gamma\alpha} + A_{\alpha\beta} = (g^{-1}dg)_{\alpha\beta\gamma}$</p> <p>$\Rightarrow dA_{\beta\gamma} + dA_{\gamma\alpha} + dA_{\alpha\beta} = 0$</p>	<p>$U(1)$-bdl.</p> <p>$g_{\alpha\beta} : U_\alpha \cap U_\beta \rightarrow U(1)$</p> <p>Connect². $A_\beta - A_\alpha = g_{\alpha\beta}^{-1} dg_{\alpha\beta}$</p> <p>$\rightsquigarrow$ 1-cocycle w/ values in closed 2-forms.</p>
---	--

$$0 \rightarrow T^* \rightarrow E \rightarrow T \rightarrow 0 \quad \text{w/ } (\cdot, \cdot), [\]$$

Def^y: A generalized metric in E is a subbdl $V \subset E$ of rank n s.t. $(\cdot, \cdot)|_V > 0$.

Locally, V is a graph of $h_\alpha: T \rightarrow T^*$
 $h_\alpha = g_\alpha + F_\alpha \in \text{Sym}^2 T^* \oplus \Lambda^2 T^*$

On $U_\alpha \cap U_\beta$, $g_\alpha = g_\beta \rightsquigarrow$ global metric
 $F_\beta - F_\alpha = B_{\alpha\beta}$.

$$\left. \begin{array}{l} ()|_V > 0 \\ ()|_{T^*} = 0 \end{array} \right\} \Rightarrow \begin{array}{c} E \rightarrow T \rightarrow 0 \\ U \\ \downarrow \cong \\ V \end{array}$$

$$\rightsquigarrow \nabla_X v = \pi_V [X^\flat, v].$$

$$\begin{aligned} & \left[\frac{\partial}{\partial x_i} - g_{ik} dx_k + F_{ik} dx_k, \frac{\partial}{\partial x_j} + g_{jl} dx_l + F_{jl} dx_l \right] \\ &= \text{Levi-Civita} + \frac{\partial F_{jl}}{\partial x_i} dx_l - \frac{\partial F_{ik}}{\partial x_j} dx_k - \frac{1}{2} d(F_{ji} - F_{ij}) \\ &= \left(\frac{\partial F_{jl}}{\partial x_i} - \frac{\partial F_{il}}{\partial x_j} - \frac{\partial F_{ji}}{\partial x_l} \right) dx_l \\ & \text{skew-torsion} \quad dF_\alpha = H \in \Omega^3(M) \end{aligned}$$

\rightsquigarrow Riemannian metric w/ skew-torsion.

Example 1. Lie group G , $\nabla_X Y = 0$
 w/ Bi-inv. metric for left-inv. v.f.
 \rightsquigarrow flat w/ skew-torsion.

Example 2. Bismut connection. On a Hermitian mfd, $\exists!$ connection w/ skew-torsion which preserves metric & cpx str..

$$H = d^c \omega = J d\omega \quad (\because J\omega = \omega).$$

$$dH = 0 \iff dd^c \omega = 0. \quad \text{SKT metric}$$

Strong Kähler w/ torsion

§ Generalized complex structure

$$T \oplus T^*, (\cdot, \cdot), [\cdot, \cdot]$$

Ordinary: $J: T \rightarrow T$ $J^2 = -1$
 $+i$ eigenspace in $T \otimes \mathbb{C} \xrightarrow{\sim} T^{1,0} \ni X, Y$
 integrability: $[X, Y] \in T^{1,0}$.

Def. A generalized cx. str. is

- $J: T \oplus T^* \rightarrow T \oplus T^*$, $J^2 = -1$
- $(Ju, v) = -(u, Jv)$
- $(+i)$ -eigenspace $\subset (T \oplus T^*) \otimes \mathbb{C}$, call $E^{1,0}$
 sections closed under Courant bracket

Note: $[u, fv] = f[u, v] + (Xf)v - (u, v)df$
 $Ju = u \Rightarrow i(u, u) = -(Ju, v) = 0 \Rightarrow \underbrace{\quad}_0 \Rightarrow$ tensorial.

Examples: 1. Cx. mfd. $E^{1,0} = \langle \frac{\partial}{\partial \bar{z}_i}, dz_i \rangle$

2. Symplectic mfd. $E^{1,0} = \langle \frac{\partial}{\partial x^i}, \underbrace{-i\omega_{jk} dx^k}_{B\text{-field}} \rangle$.

$$T \subset T \oplus T^*$$

$$\frac{\partial}{\partial x^i} \mapsto \frac{\partial}{\partial x^i} - i\omega_{jk} dx^k$$

closed 2-form preserves $[\cdot, \cdot]$

3. Holomorphic Poisson manifold

Recall. $\sigma \in \Gamma(\Lambda^2 T) \mapsto \sigma: T^* \rightarrow T$

$$\sigma(df) = X_f \quad \text{Hamil. v.f.}$$

$$\{f, g\} := \sigma(df)(g) = \sigma(df, dg) = -\{g, f\}$$

$$\sigma(d\{f, g\}) = [X_f, X_g] \quad \text{Lie bracket}$$

↑ integrability condition.

$$E^{1,0} = \langle \frac{\partial}{\partial \bar{z}_i}, dz_j - \sigma(dz_j) \rangle$$

integ.?

$$\begin{aligned}
& [dz_i - \sigma(dz_i), dz_j - \sigma(dz_j)] \\
&= [\sigma(dz_i), \sigma(dz_j)] - d\{z_i, z_j\} + d\{z_j, z_i\} + \frac{1}{2} d(\{z_i, z_j\} - \{z_j, z_i\}) \\
&= \sigma d\{z_i, z_j\} - d\{z_i, z_j\}.
\end{aligned}$$

(or simply "B-field" transf. w/ σ).

$M^{2\mathbb{C}}$ complex surface (integ. autom.) w/ $\Lambda^2 T = K^{-1}$ $H^0(M, K^{-1}) \neq 0$

Note: $E^{1,0} \subset (T \oplus T^*)^c$ max. isotropic
 \sim pure spinor \rightsquigarrow forms $\varphi \in \Lambda T^* \otimes \mathbb{C}$
 (pure \sim ann (φ) has max dim).

Eg. 1. $\varphi = dz_1 \wedge \dots \wedge dz_n$ 2. $\varphi = e^{i\omega}$.
 $\text{Ann}(\varphi) = E^{1,0}$

Require $d\varphi = 0$ \sim gen. CY.

Integ. $\iff d\varphi = \theta \cdot \varphi$ $\exists \theta \in C^\infty((T \oplus T^*)^c)$
 \uparrow Clifford product

uv $u \mapsto \tilde{u}$
 \parallel $X + \zeta$ $X - d\zeta \in \text{Lie}(\Omega_{\mathbb{C}}^2 \times \text{Diff}(M))$
 $\tilde{u}(v)$

$L_u \sim$ Lie derivative action of \tilde{u} .

$$L_u \varphi = d(u \cdot \varphi) + u \cdot (d\varphi).$$

Assume $d\varphi = \theta \cdot \varphi$

$$u \cdot \varphi = 0 = v \cdot \varphi$$

$$\begin{aligned}
0 &= L_v(u \cdot \varphi) = (L_v u) \cdot \varphi + u \cdot \underbrace{L_v \varphi}_{d(v \cdot \varphi) + v \cdot d\varphi} \\
&= (L_v u) \cdot \varphi + \underbrace{u \cdot v \cdot \theta \cdot \varphi}_0 \leftarrow (v \cdot \theta + \theta \cdot v = 2(v, \theta))
\end{aligned}$$

$$2[u, v] \varphi = (L_v u - L_u v) \cdot \varphi = 0$$

#

Note. $df \in T^* \oplus T \ni J(df) =: X + \zeta$

$X - d\zeta$ is a symmetry of the gen. cx. str.

Symplectic $J(df) = X_f$ Hamiltonian v.f.

I-Cx. case $J(df) = I(df) \rightsquigarrow d(I df) \leftarrow \begin{matrix} \text{closed (L.I)} \\ \text{real form.} \end{matrix}$

$$\Omega^2_{ce} \rtimes \text{Diff}$$

§ 7. The $\bar{\partial}$ -complex

$$(T \oplus T^*)^c = E^{1,0} \oplus E^{0,1}$$

$$\bar{\partial}_J f := (df)^{0,1}$$

1. cx mfd. $\bar{\partial}_J f = \bar{\partial} f$

2. sympl. mfd. $\bar{\partial}_J f = \frac{1}{2}(iX_f + df)$

3. holo. Poisson $\bar{\partial}_J f = \bar{\partial} f + \sigma(\partial f) - \bar{\sigma}(\bar{\partial} f)$

$$\bar{\partial}_J : C^\infty(M) \rightarrow C^\infty(E^{0,1}) \quad (E^{0,1})^* \simeq E^{1,0}$$

$$2 \bar{\partial} \alpha(u, v) = X \alpha(v) - Y \alpha(u) + \alpha([u, v])$$

$$\begin{cases} u = X + \zeta \\ v = Y + \eta \end{cases} \in E^{0,1}$$

extends

$$\rightsquigarrow \bar{\partial}_J : C^\infty(E^{0,1}) \longrightarrow C^\infty(\Lambda^2 E^{0,1})$$

$$(\bar{\partial}_J)^2 = 0 \quad ? \quad \left(\begin{array}{l} \text{Only work because of isotropic cond.} \\ \Rightarrow \text{Jacobi identity holds for } C^\infty(E^{0,1}) \end{array} \right)$$

$$\rightsquigarrow \bar{\partial}_J : C^\infty(\Lambda^p E^{0,1}) \rightarrow C^\infty(\Lambda^{p+1} E^{0,1}), \quad \bar{\partial}_J^2 = 0$$

Ex 1. cx str. $E^{0,1} = \bar{T}^* \oplus T$

$$\Lambda^p E^{0,1} = \bigoplus_{\ell+m=p} \Lambda^\ell \bar{T}^* \otimes \Lambda^m T$$

$$\bar{\partial}_J = \bar{\partial} : \bigoplus \Omega^{0,\ell}(\Lambda^m T) \rightarrow \bigoplus \Omega^{0,\ell+1}(\Lambda^m T)$$

Twist. (on a honest cpx mfd.).

replace $T \oplus T^*$ by E .
(\sim closed 3-form H)

patch by $B_{\alpha\beta}$

$B_{\alpha\beta}^{(1)}$ - transf. (\sim cpx. holo. bdl.)

\rightarrow Add $H^{1,2}: \Omega^{0,l}(\Lambda^m T) \rightarrow \Omega^{0,l+2}(\Lambda^{m-1} T)$
to $\bar{\partial}_J$.

(elliptic complex.)

Note: 1st order deform of gen. cx. str. (at a cpx str. param. by $H^0(\Lambda^2 T) \oplus H^1(T) \oplus H^2(O)$.)

Obstruction $\in H^0(\Lambda^3 T) \oplus H^2(T) \oplus H^3(O)$.
 $\oplus H^1(\Lambda^2 T) \dots$

§ 8 Generalized Kähler manifolds

Kähler \sim cpx + symp.

J_1 $J_2 \leftarrow$ 2 gen. cx. str.

Def. A gen. Kähler mfd. consists of 2 gen. cx. str. J_1, J_2 satisfying

$$J_1 J_2 = J_2 J_1 \neq (J_1 J_2 u, u) > 0.$$

Theorem. M^{2n} Gen. Kähler \Rightarrow

• metric g

• 2 integ. Hermitian cx. str. I^+, I^-

• metric conn. ∇^+, ∇^- w/ skew torsion $\pm H$

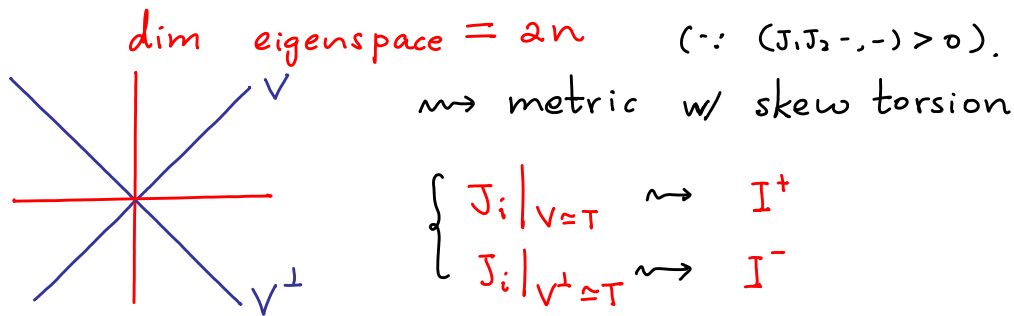
s.t. $\nabla^+ I^+ = 0 = \nabla^- I^-$

• closed 2-form

(equiv. up to B-field action)

(Gate-Hull-Rocek 1984).

$(J_1, J_2)^2 = 1 \rightsquigarrow (\pm 1)$ eigenspaces.



Theorem (Goto) Let M be a cpt. Kähler mfd. w/ a holo. Poisson str. σ . Let $J_i(t)$ be the gen. cx. str. def^d by $t\sigma$, then for any small t \exists analytic family of gen. Kähler str. $(J_1(t), J_2(t))$ where $J_2(0) = \text{symp. str. of the original Kähler structure}$.

Note, $[I^+, I^-] \in C^\infty(\wedge^2 T)$ is real part of holo. Poisson.

Def. A generalized holo. bdl. on a gen. cx. mfd is a VB together with an operator

$$\bar{D} : C^\infty(V) \rightarrow C^\infty(V \otimes E^{0,1})$$

such that $\bar{D}(fs) = s \otimes \bar{\partial}_J f + f \bar{D}s$, $\bar{D}^2 = 0$

Example: 1. Any gen. cx. str. has canonical bundle $K \subset (\wedge^* T^*)^c$ as gen. holo. bdl.

$$u \in E^{1,0} \iff u \cdot \varphi = 0 \quad \text{for } \varphi \in (\wedge^* T^*)^c$$

fiber of $K = \mathbb{C} \cdot \varphi$

$$\text{integrability: } d\varphi = \theta \cdot \varphi \quad \exists! \theta \in E^{0,1}$$

$$\bar{D}(f\varphi) := (\bar{\partial}_J f + f \theta^{0,1}) \cdot \varphi \quad \leftarrow \text{well-def}^d.$$

$$\bar{D}^2 = 0 \iff \bar{\partial}_J \theta = 0$$

$$u, v \in E^{1,0}, \quad (\bar{\partial}_J \alpha)(u, v) = X(\alpha, v) - Y(\alpha, u) + \alpha[u, v].$$

$$L_u \varphi = d(u \cdot \varphi) + u \cdot d\varphi = u \cdot \theta \cdot \varphi = -\theta u \varphi + 2(u, \theta) \varphi$$

$$L_v L_u \varphi = 2 L_v(u, \theta) \varphi + 4(u, \theta)(v, \theta) \varphi$$

$$L_u L_v \varphi = 2 L_u(v, \theta) \varphi + 4(v, \theta)(u, \theta) \varphi$$

$$\tilde{\rightarrow} = \frac{1}{2} [u, v] \theta \cdot \varphi = 2 \frac{1}{2} ([u, v], \theta) \varphi . \quad \#$$

Eg. 2. $J =$ ordinary cx. structure.

$$\bar{D} : V \rightarrow V \otimes (T^{0,1*} \oplus T^{1,0})$$

$$\bar{D}(fs) = s \otimes (\underbrace{\bar{\partial} f}_{\text{holo.}}, 0) + f \bar{D}s$$

$$\bar{D}s = (\underbrace{\bar{\partial}_A s}_{\text{usual holo. str. for } V}, \phi s) \quad \phi \in C^\infty(\text{End } V \otimes T^{1,0})$$

$$0 = \bar{D}^2 s = (\underbrace{\bar{\partial}_A^2 s}_{\text{holo. str. on } V}, (\bar{\partial}_A \phi) s, \phi \wedge \phi s) \quad \phi \text{ is holo} \quad \phi \wedge \phi = 0 \in H^0(\text{End } V \otimes \wedge^2 T)$$

§ Generalized Complex Submanifolds.